



BATHYSAT: Feedback on the deployment of the first services

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From light to Earth information

Develop the uses
of spectral imagery
for mapping

Created in
2016

A team of
12 people
+ temp / trainees



3

Technical Units

**SENSING
/
MAPPING**

ANALYTICS

SOFTWARE

Operational Services

Data
acquisition
Aircrafts
and UAVs

Image
analysis
and
processing

Dev of
processing
and viz
infrastructures

Apps : maritime & agronomy

Hydrography and costal moprhodynamics,
Coastal biodiversity, dynamics of habitats, macrofaune,
Turbidity monitoring, coastal archeology, phenotyping

FlySpec

Hypip

Bathysat

STORMM

SWIM

Littoviz

...

...

...

Use case: Saint-Pierre-et-Miquelon, North Atlantic



Direction des Territoires, de l'Alimentation et de la Mer de Saint-Pierre et Miquelon

- ❑ 0-10m Bathymetric DEM requested by DTAM, the public office in charge of the administration of the coastal domain
- ❑ Exail / Hytech : **What about using SDB in shallow waters and DriX MBES in higher depths ?**
 - Increase safety of the DriX navigation by avoiding shallow waters
 - Enable full coverage using MBES where SDB can not (turbid area)
 - Save (a large amount of) money by reducing DriX costs !!

Bathysat[®]



SWIM[®] :

Shallow water mapping using optical remote sensor(s)

INVERSION MODEL : MODULE SWIM[®]

Remote-sensing
reflectance under
the water surface

=

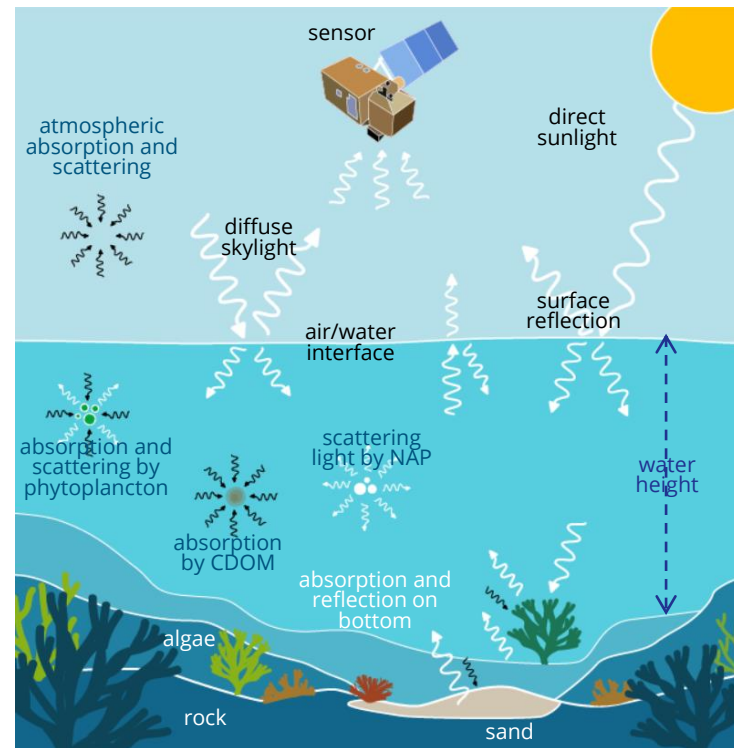
Water column
reflectance

+

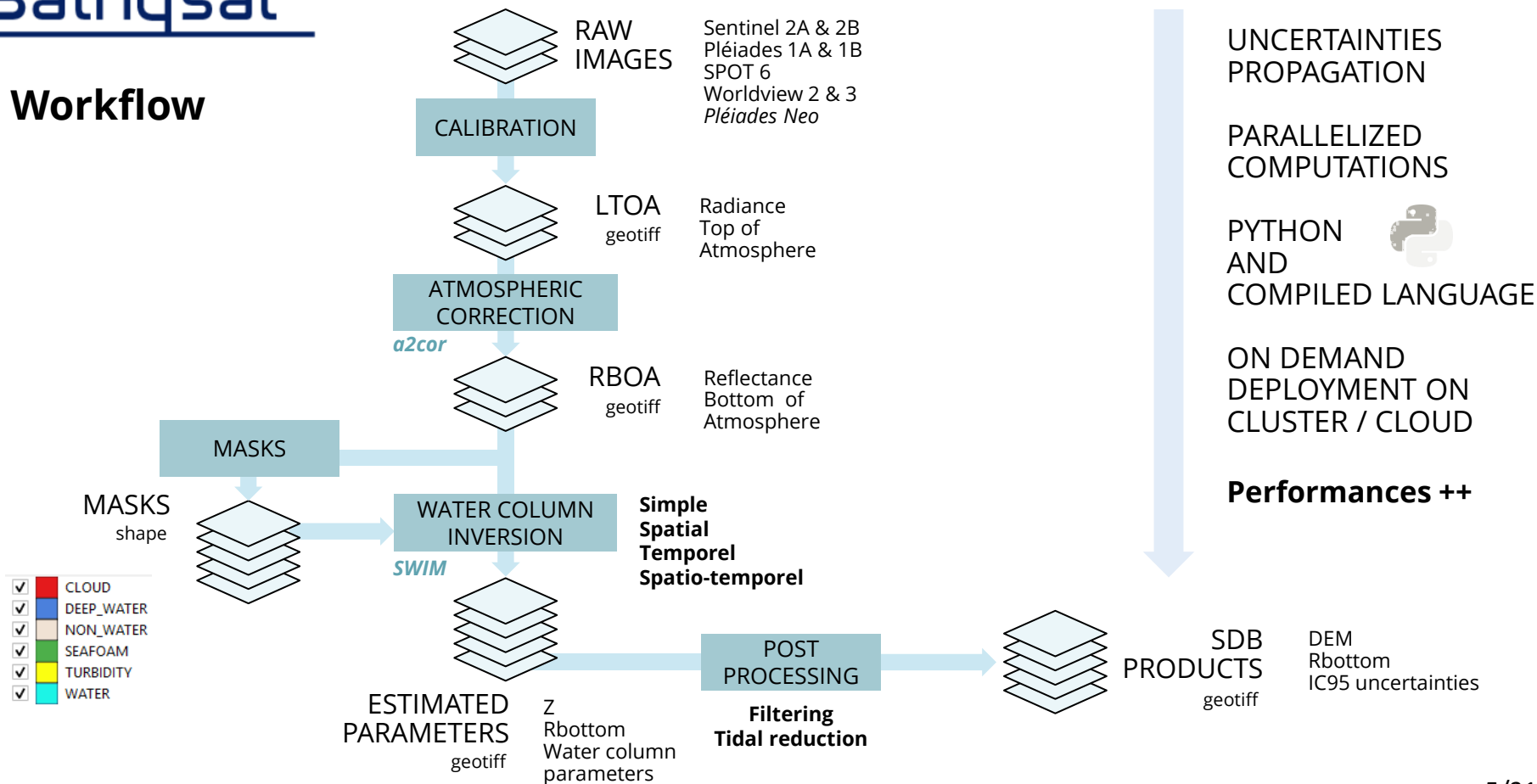
Bottom reflectance

$$R_{rs}^- = R_{rs}^\infty (1 - A_1 e^{-(K_d + k_{uW})Z}) + A_2 R_{rs}^B e^{-(K_d + k_{uB})Z}$$

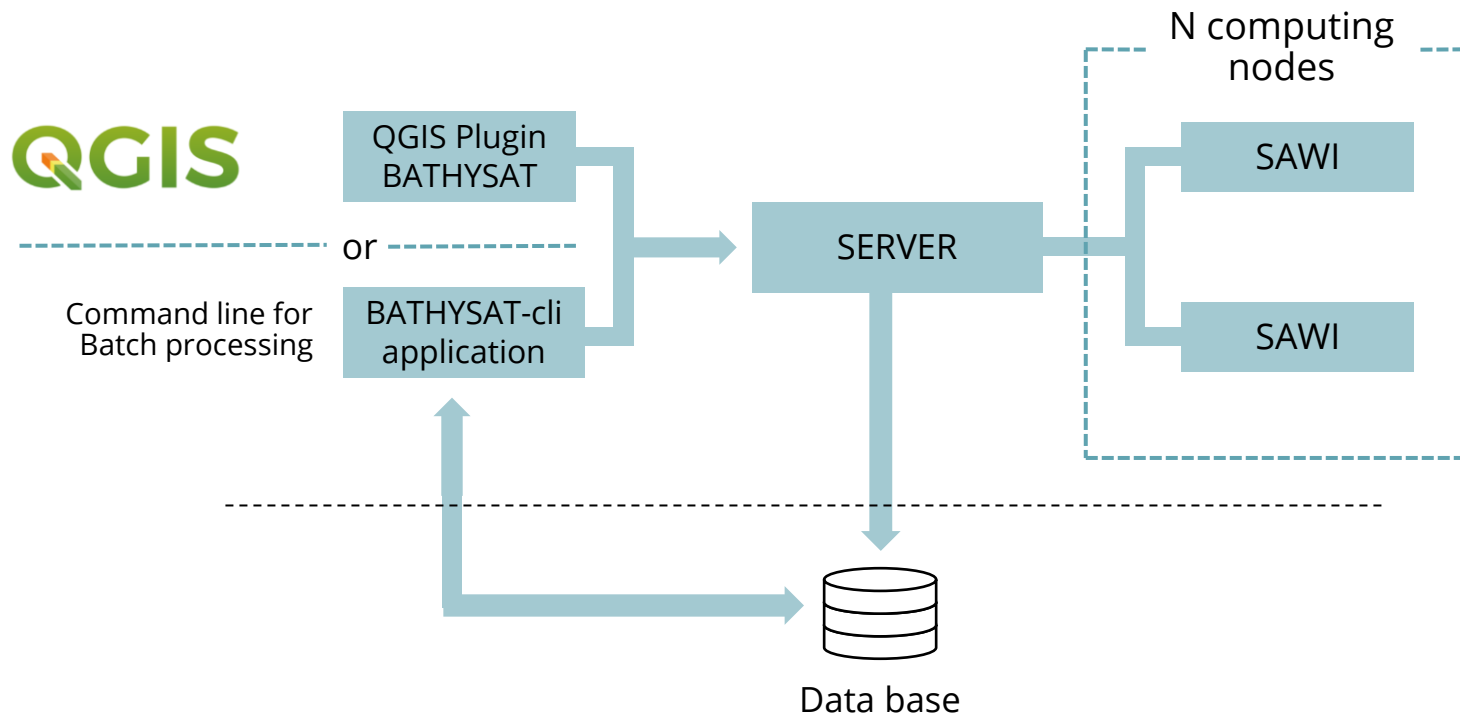
PARAMETERS ESTIMATION BY INVERSION OF THE RADIATIVE TRANSFER MODEL



Workflow



General architecture

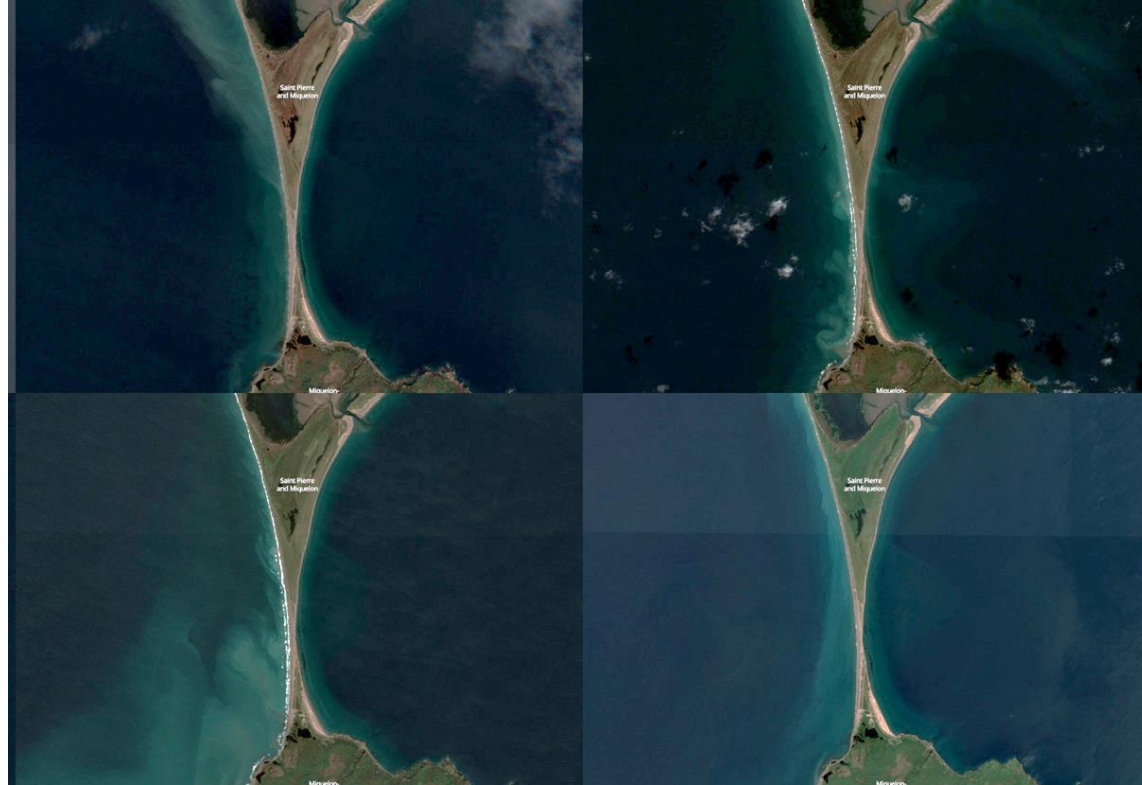


Implementation on a local server or on the AWS cloud

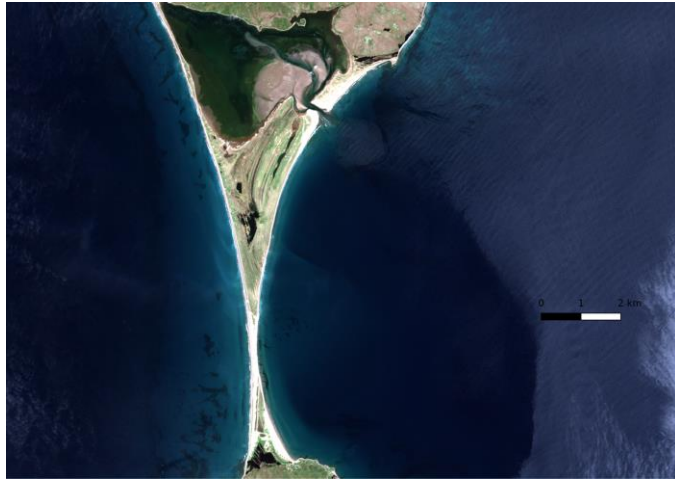
Area of interest : usually turbid, especially in the West



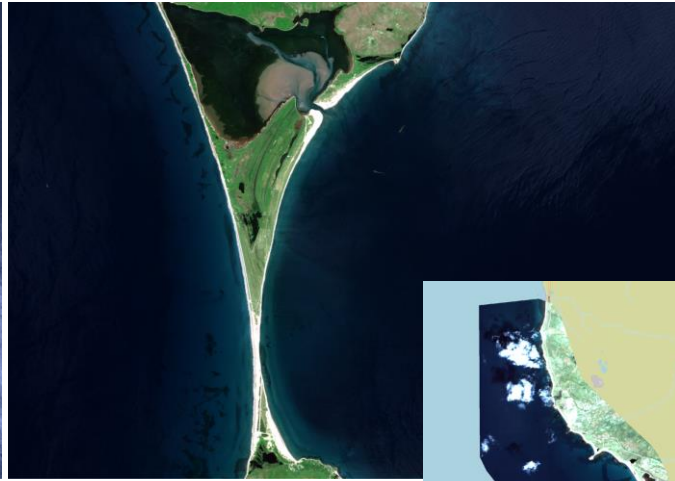
Typical S2 imagery
See plumes on the western part



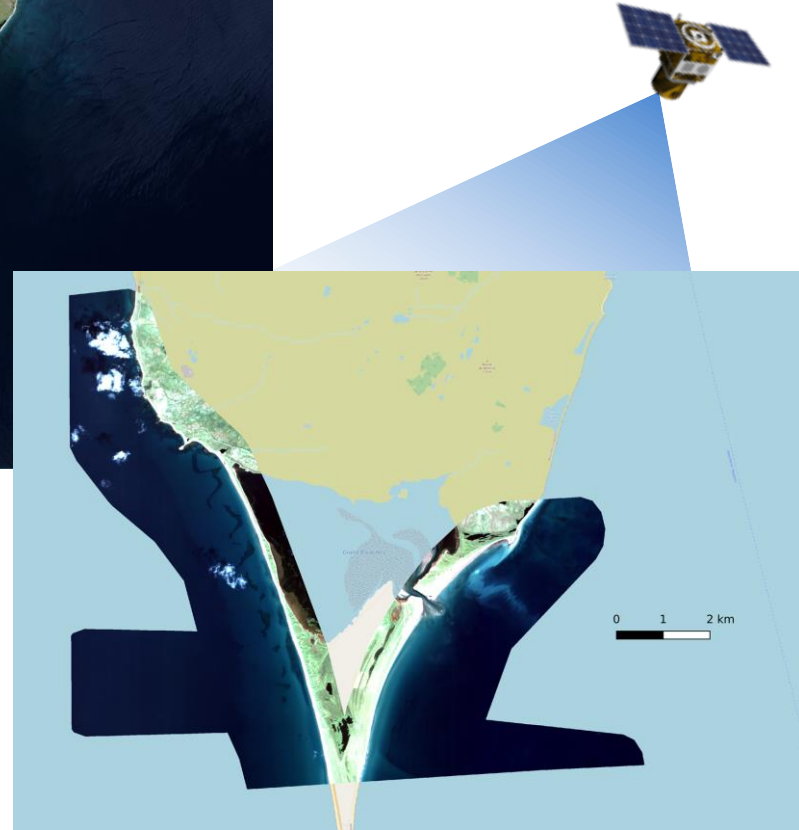
Step 1: Get satellite data \Rightarrow Sentinel-2 + Pleiades



S2 - 08/06/2022

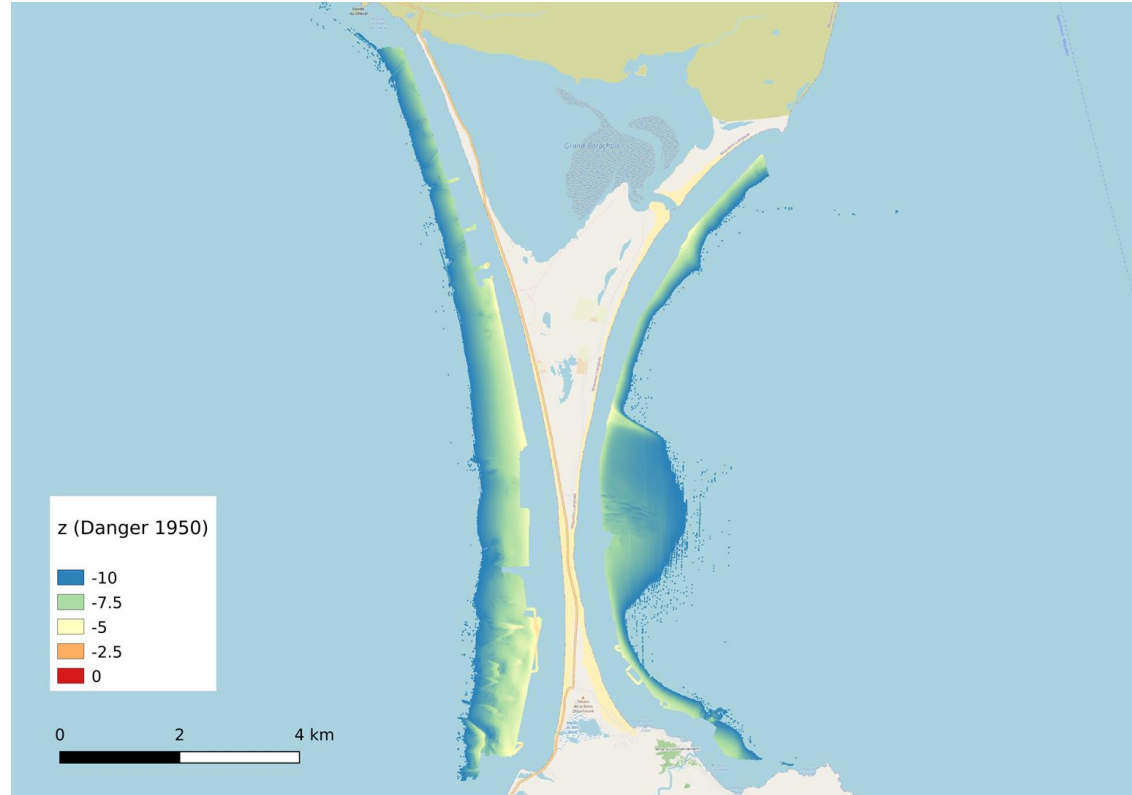


S2 - 08/07/2020



Pléiades - 08/09/2022

Step 2 : Get MBES DriX data (~5 to ~10m deep)

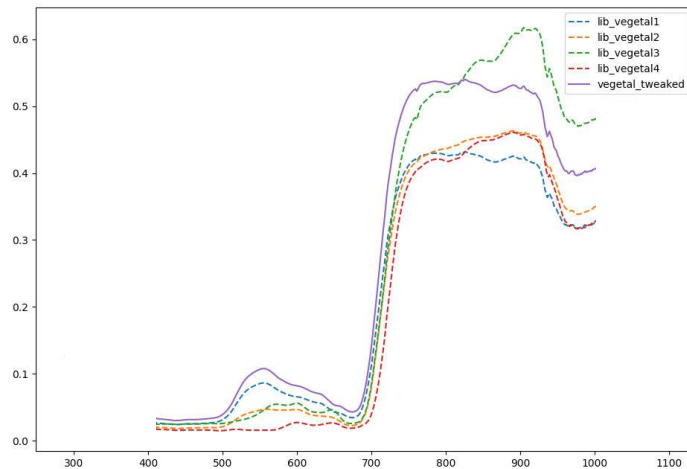
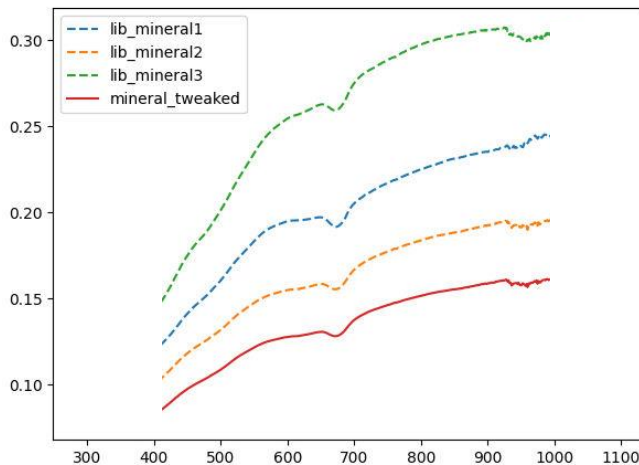


Step 3 : Find MBES / SDB overlapping areas and adjust the bottom model in the RTM

Bathysat®

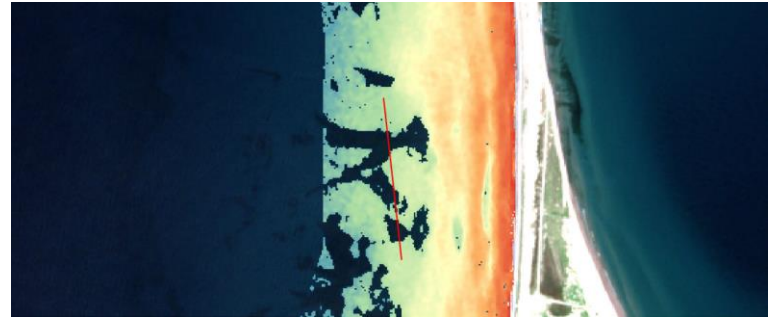
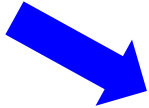
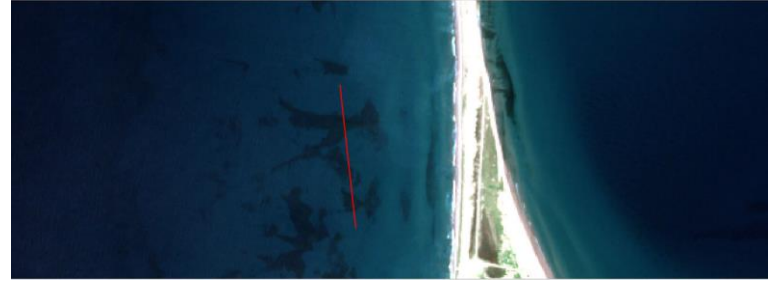
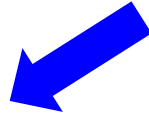
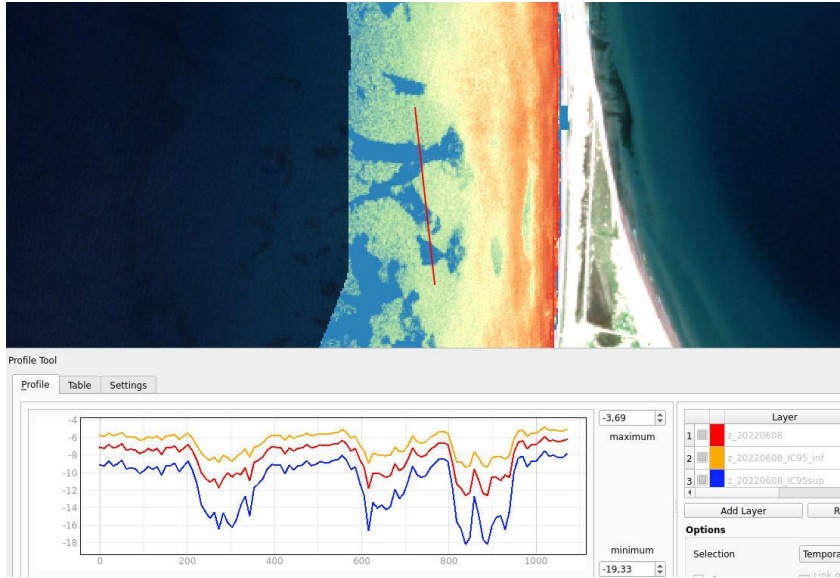
Operation modes

- ☐ Auto / semi-auto modes
- ☐ With / without in situ data
- ☐ Simple / spatial / temporel modes
- ☐ Analytical estimation of uncertainties



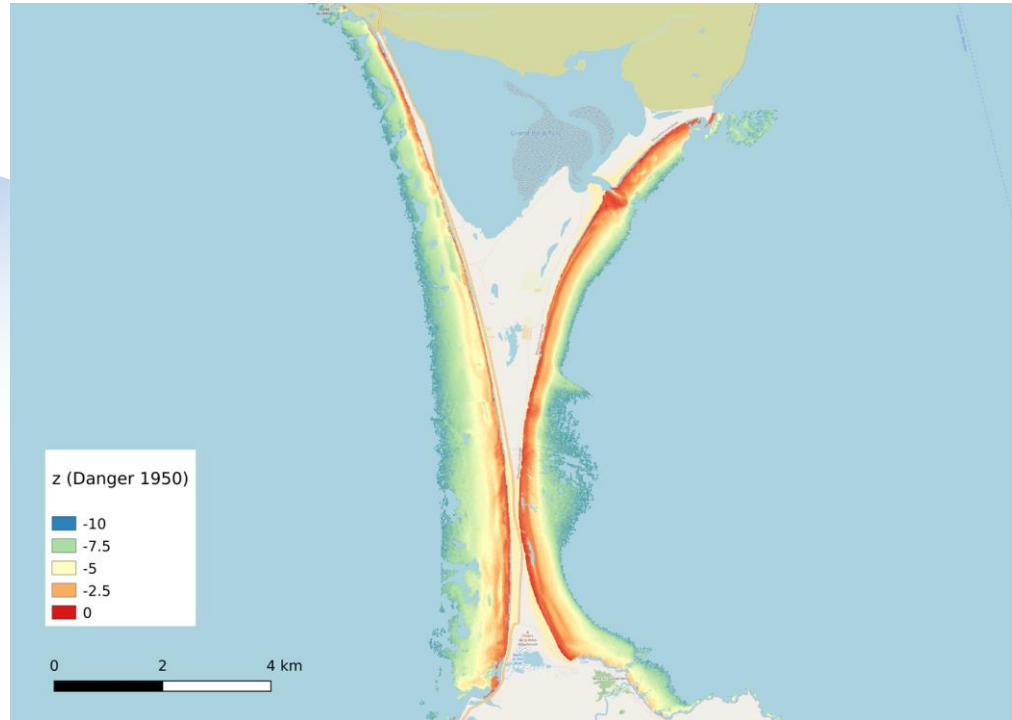
St-Pierre : bottom model adjusted over the DriX MBES / SDB overlap areas

Step 4: Compute SDB + uncertainties, then filter

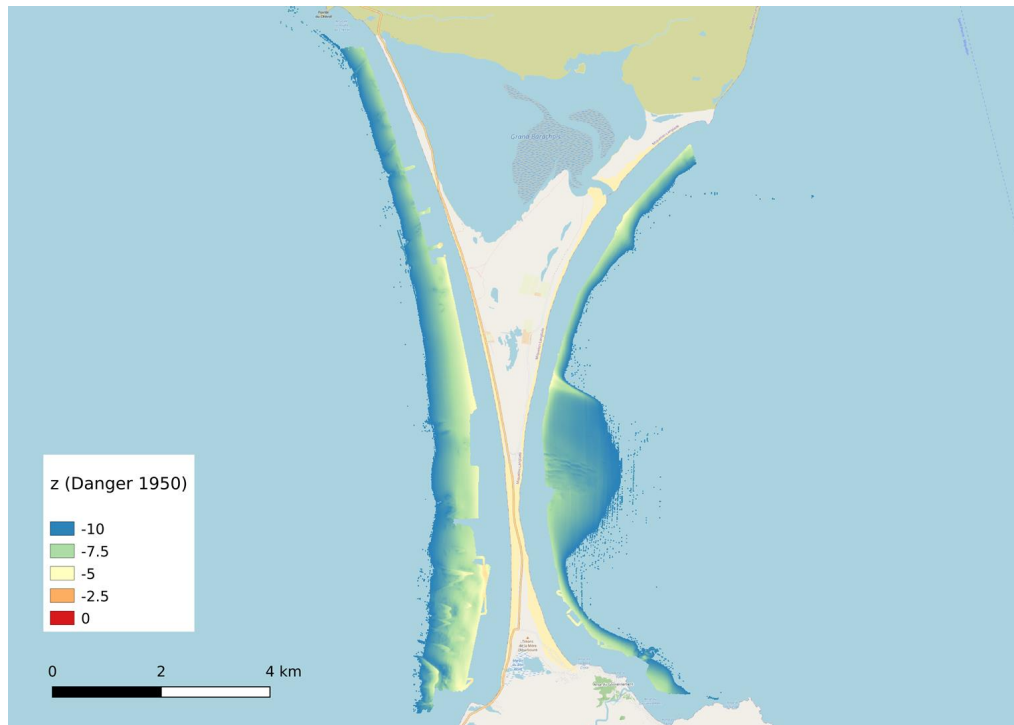


Dark bottoms filtered due to high uncertainty

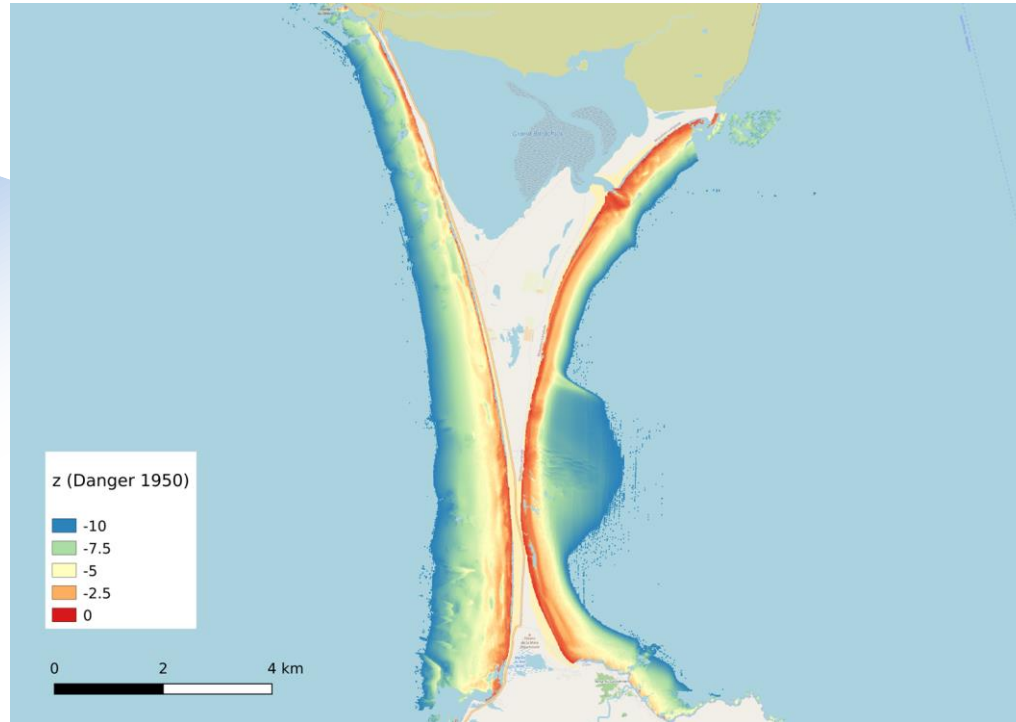
Then compute SDB on the full area 0 to ~7m



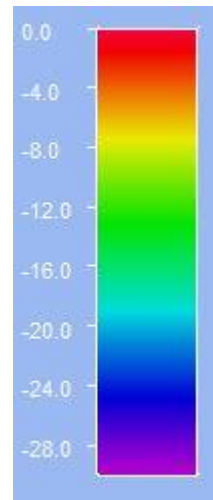
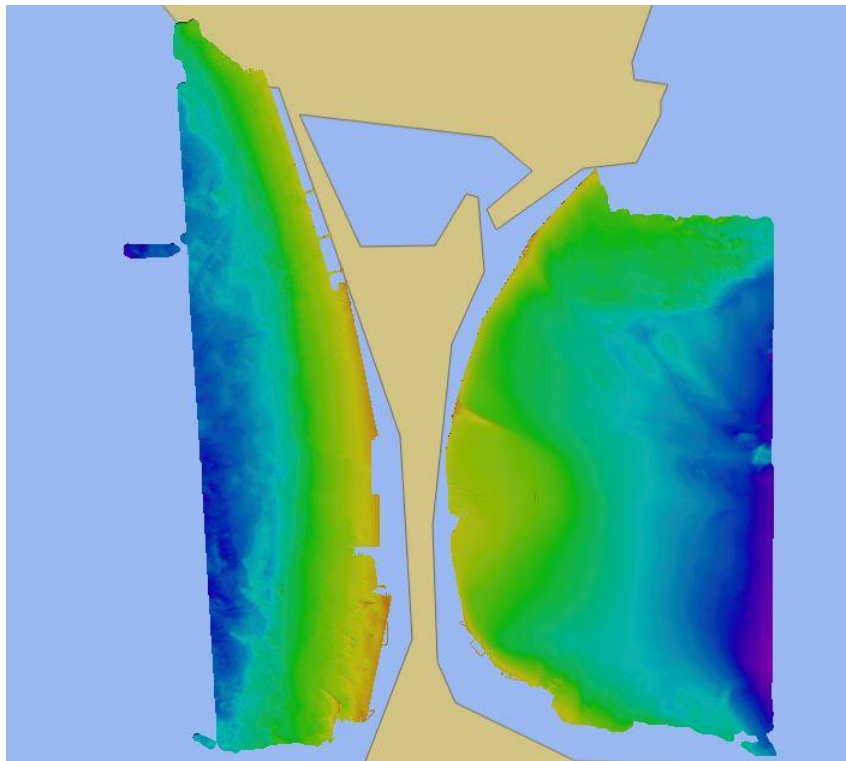
Get Back MBES DriX data ~5 to ~10m



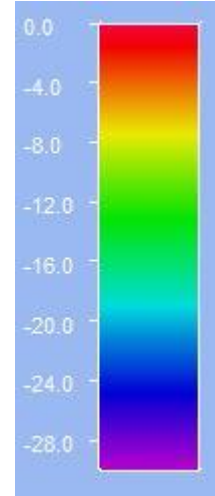
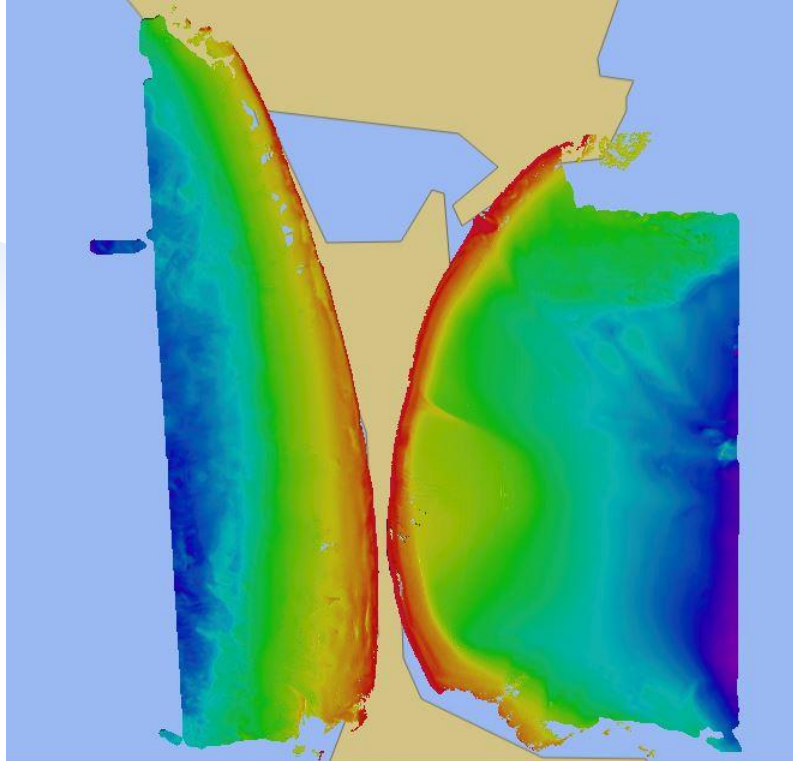
And then fuse SDB + MBES DriX \Rightarrow 0 to 10m



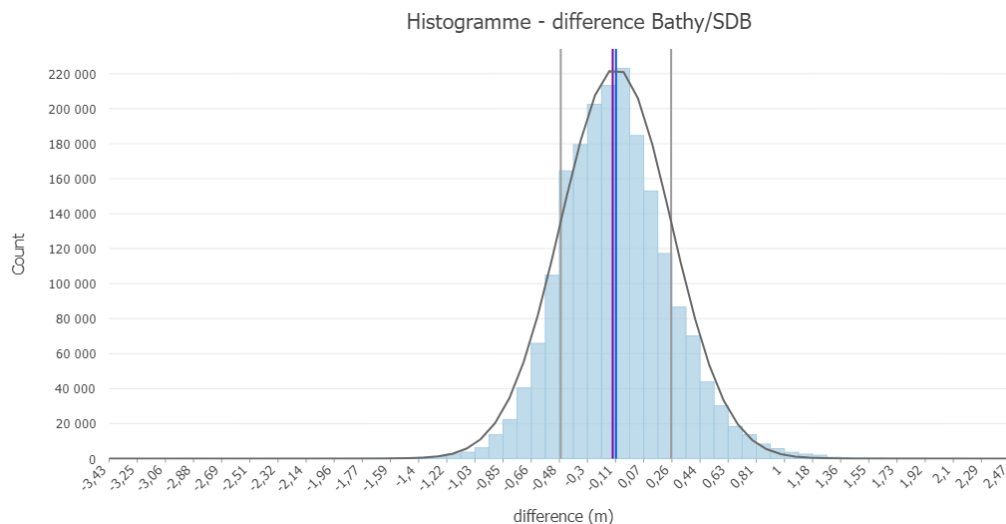
Then extend DriX to 30m



And then fuse SDB + MBES DriX \Rightarrow 0 to 30m



Precision / accuracy reached



Accuracy / Precision evaluated in the overlapping MBES / SDB area :

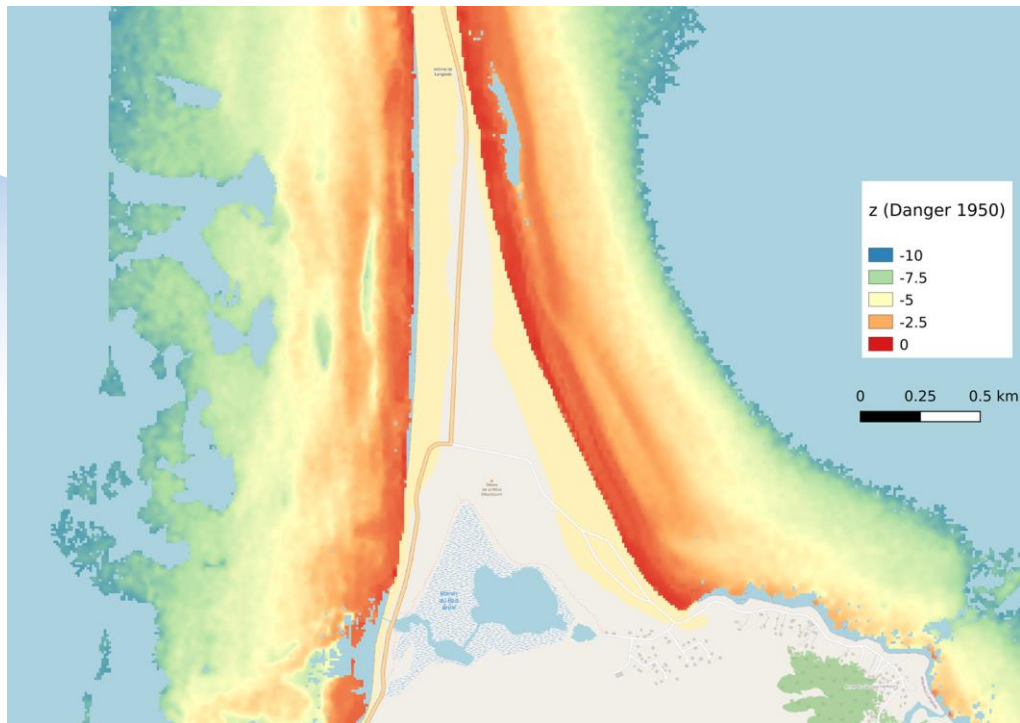
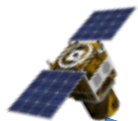
Bias : **10.9 cm**

σ : **36.2 cm**

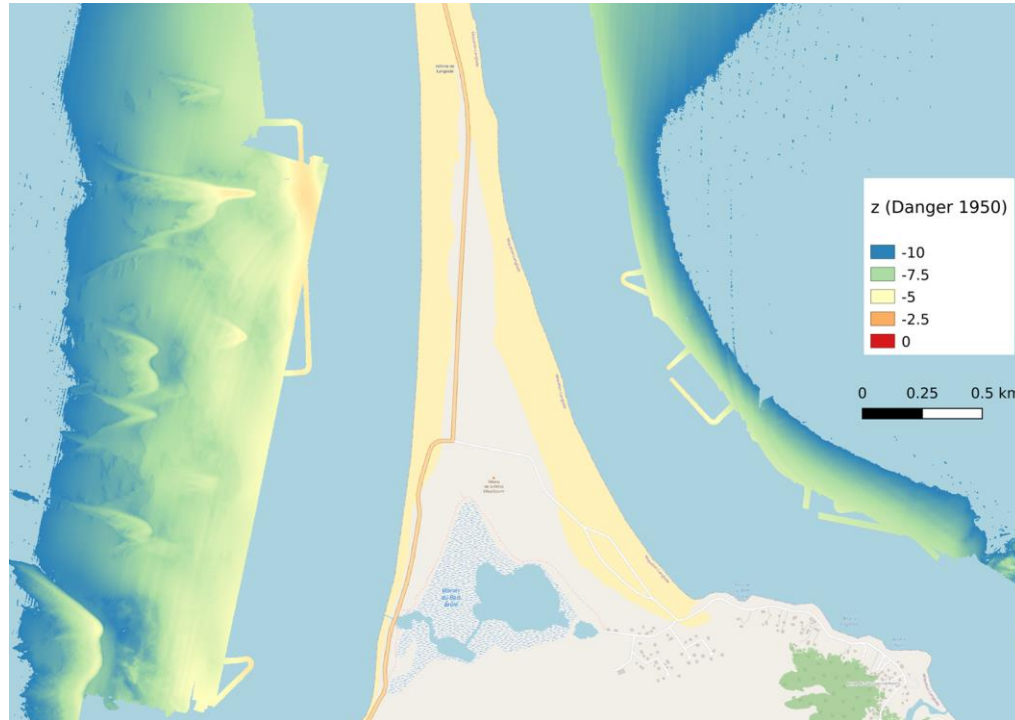
Overlapping area being mostly in the highest SDB depths (~5 to 7m)

⇒ precision / accuracy even quite better in shallower areas (< 5m)

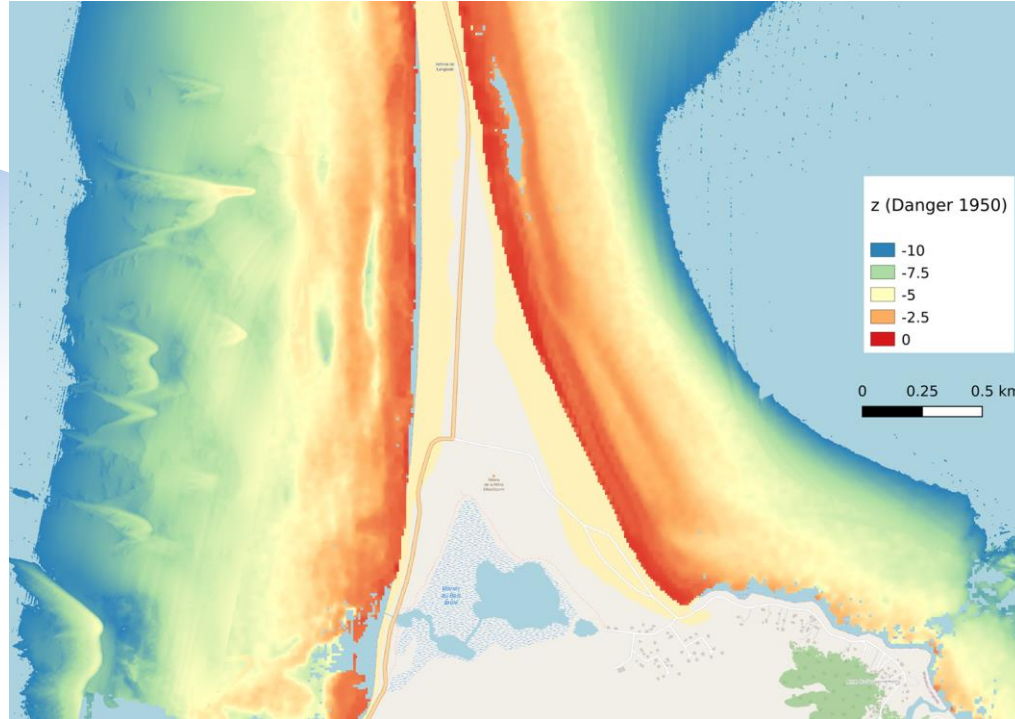
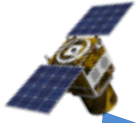
Zoom on SDB 0 to ~7m



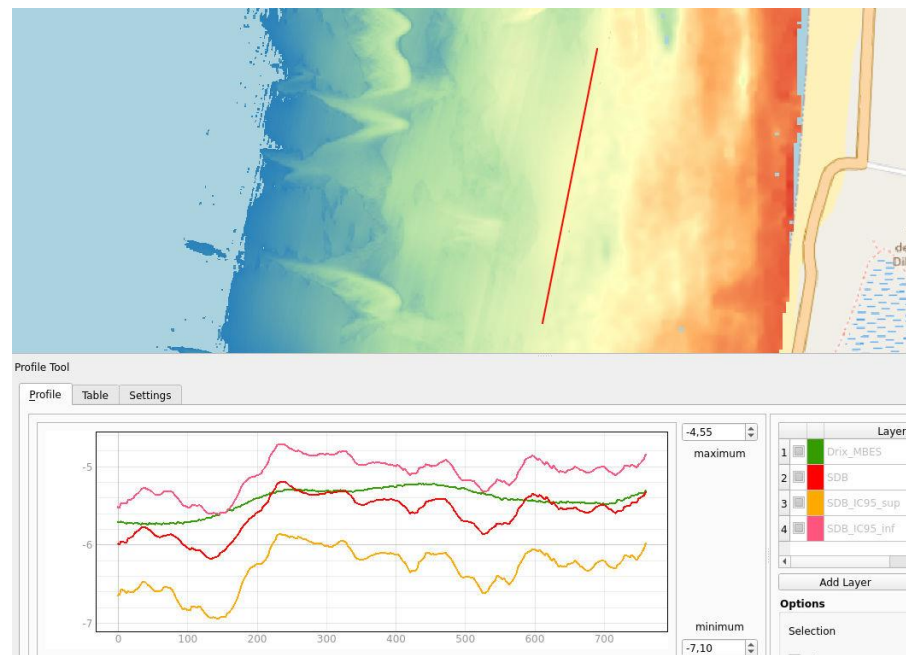
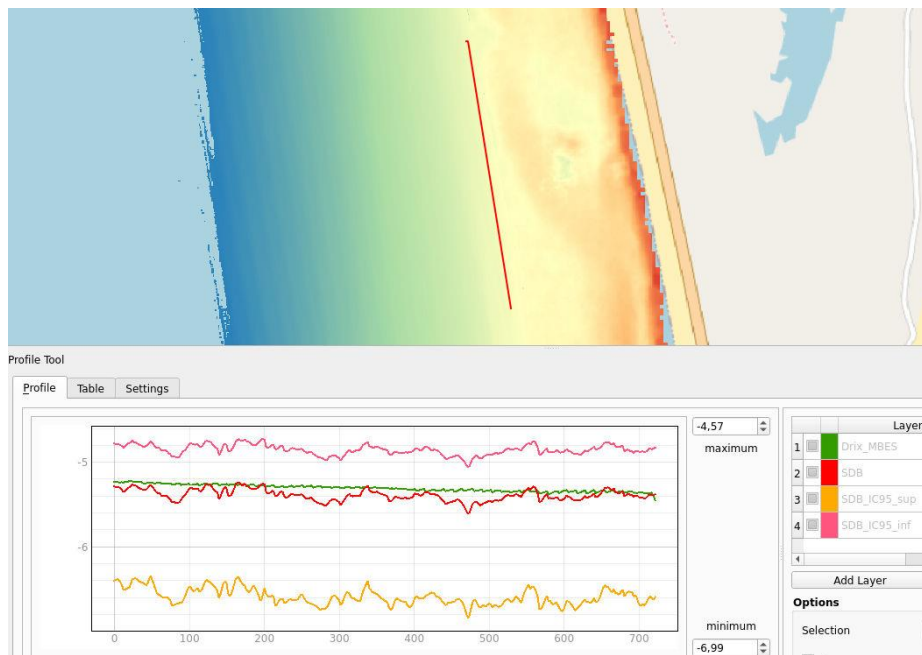
Zoom on MBES Drix ~5 to ~10m



Zoom on fused SDB + MBES Drix \Rightarrow 0 to 10m

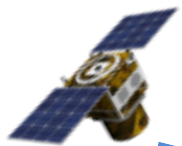


SDB / DriX MBES / Uncertainties



Lessons learned

- ❑ RT models usually need local adjustments
 - ⇒ can be done without any ground truth, but easier when z data available
- ❑ MBES data can be collected only up to the depth that can be reached with SDB (MBES data very long and costly in shallow areas)
- ❑ Then SDB can fill the gap in shallow water areas
 - ⇒ **DRIX + SDB can be used to make seamless precise coastal DEMs at costs much lower than using MBES data alone**



Thank you



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