



# Subsea detection by *Octopulse* sensor *CEDAR™ TECHNOLOGY*



Biomimetics « electric sense »



15 employees (hiring !)

<https://elwave.fr/carrieres/>

33% women



- World 's first company to offer solutions based on « electric sense »
- Awardee of the most selective French and European grants (**EURONAVAL INNOVATION AWARD 2022...**)

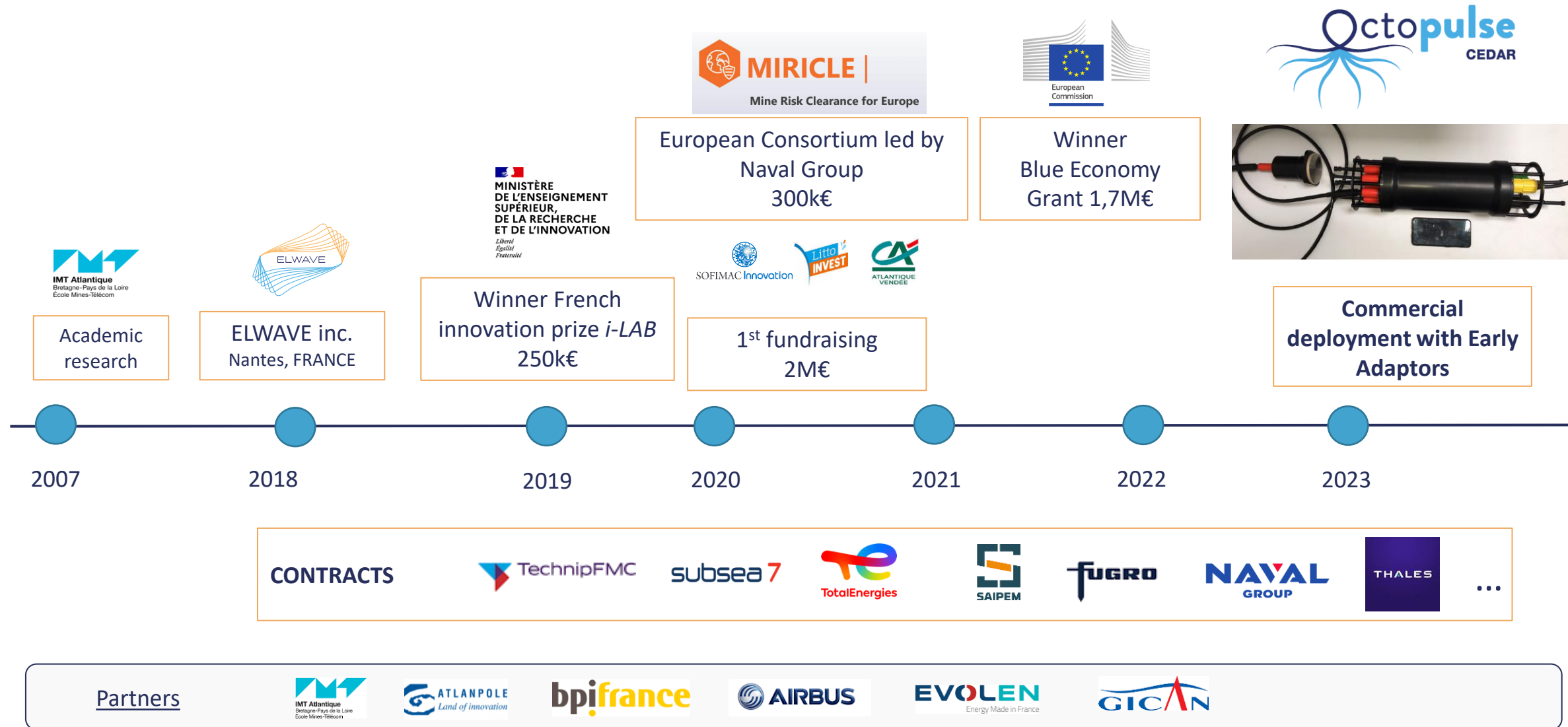
3 applicative markets



- Industrial robotics
- Energy and offshore infrastructure
- Defense and security



# HISTORY





# ENHANCED REAL-TIME 360° ELECTRIC IMAGE



## Active Electric Detection

- Emission of an alternative low frequency, low energy electric field
- Measurement of its variations
- AI & algorithms for detection, location and characterization

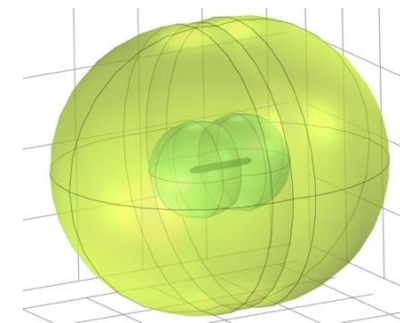
— **Real-time 360° perception** ( $4\pi$  steradian)

— **Location and characterization** (size, shape, material, alive)  
of metallic and non-metallic objects

— **Efficient for buried objects** (cable, mine/UxO, pipeline)

— **Efficient in complex environments** (turbid water, cluttered environment, ...)

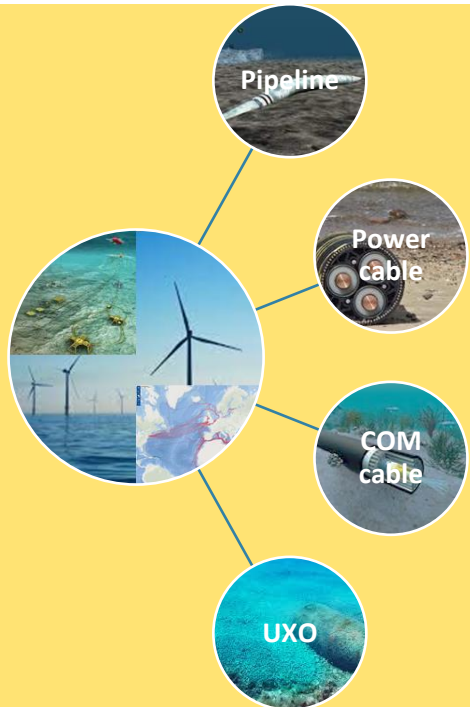
— **Integrable on any size of ROV and AUV**



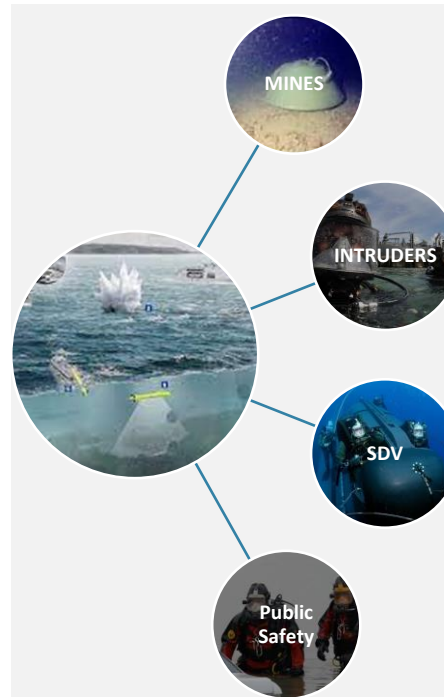
# CEDAR TECHNOLOGY, SUBSEA APPLICATIONS



## OCEAN ENERGY & COM



## OCEAN THREATS



## OCEAN RESSOURCES



## SMART ROBOTIC



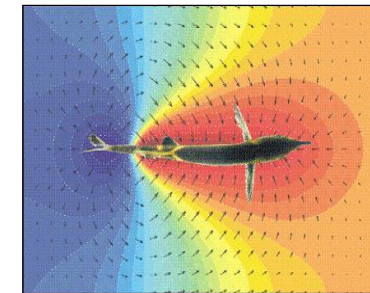
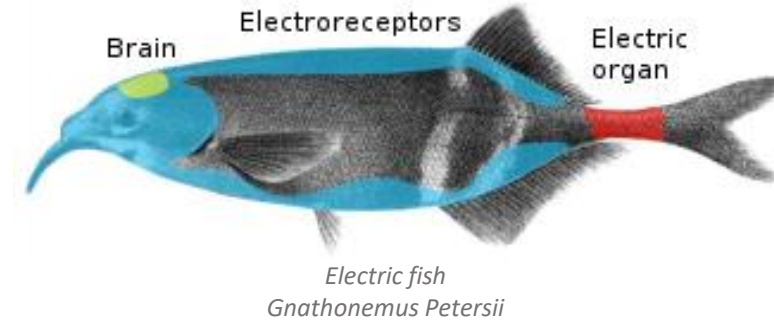
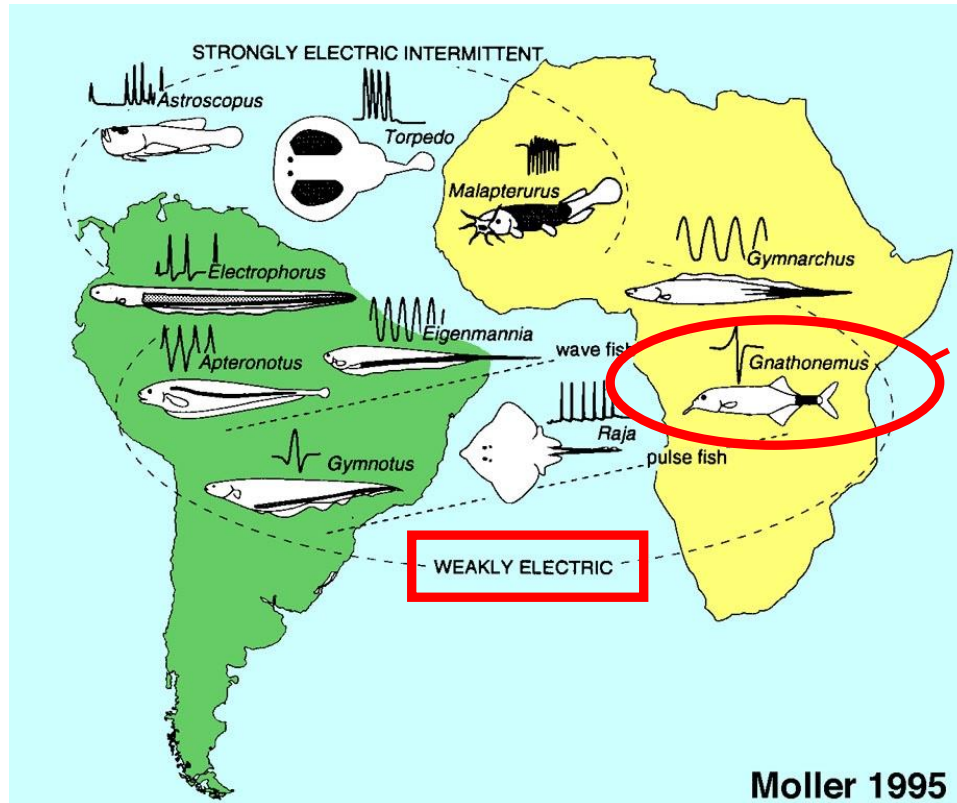




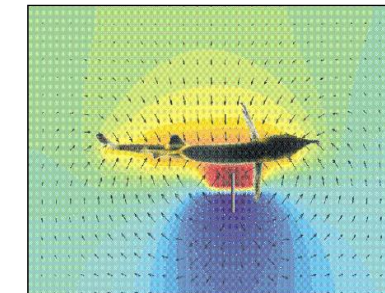
# BIO-INSPIRED TECHNOLOGY



# « Electric Sense » in Nature



Electric field generated by the fish  
without any object close to it



Electric field perturbed by an  
object close to the fish

« **Electric sense** » is the perception mode of fishes living in muddy and very cluttered tropical water in which **vision** and **acoustics** are inefficient.

Detection method:

Emission of a weakly alternative electric field

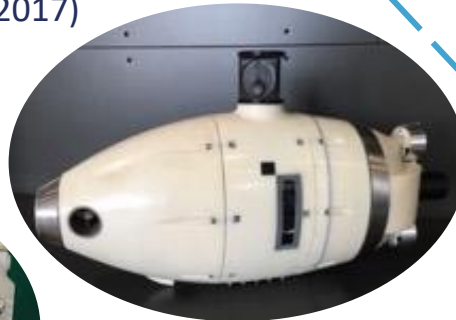
Measure of its evolution

**Real-time** data treatment for the **detection**, the **localization** and the **characterization** of object

# IMT University and Elwave collaboration



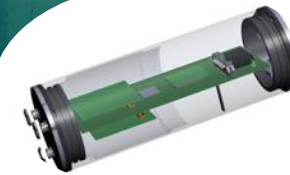
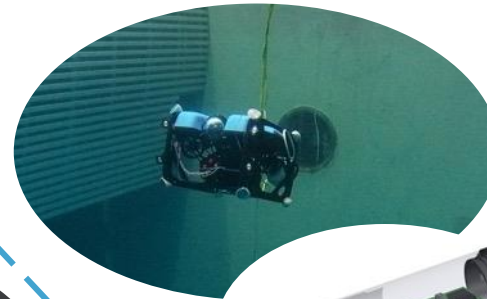
Lab Prototype V2  
(2017)



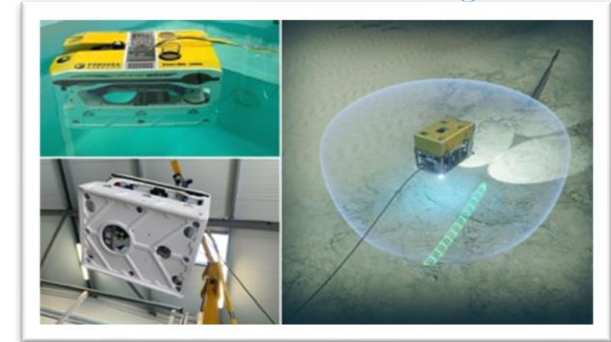
Lab Prototype V1  
(2012)



Electric probe  
(2007)



Industrial prototype  
(2020)



Commercial product *Octopulse*  
(2022)



**+ 15ans R&D**



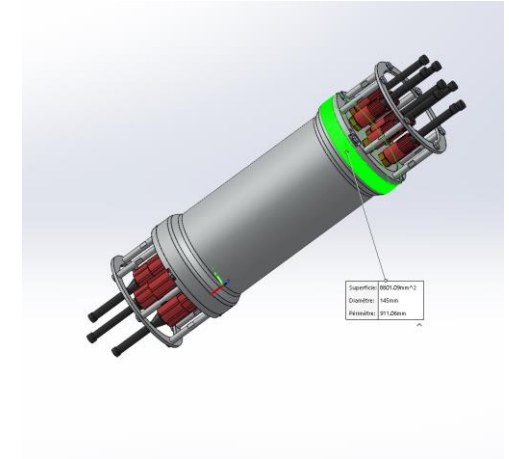
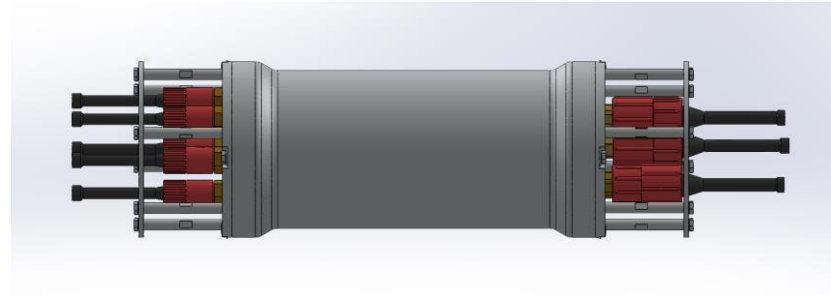
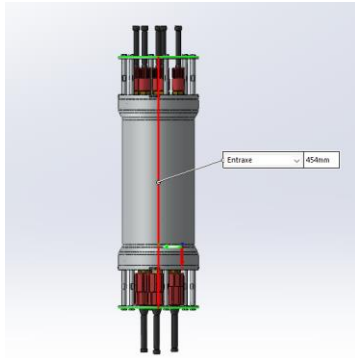


# Sensor hardwares

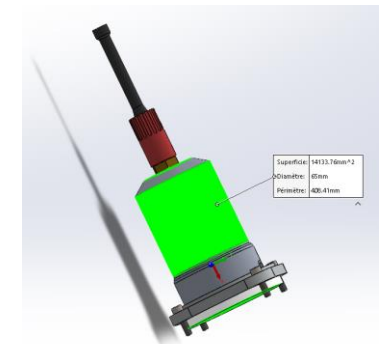
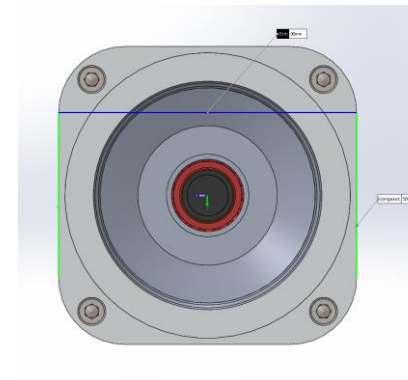
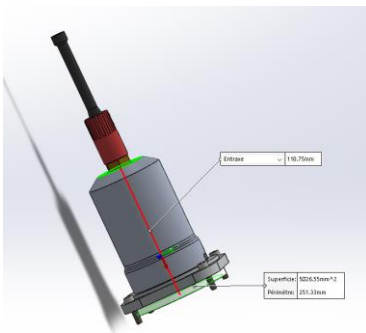
# Octopulse 300m – up to 8 electrodes – $\approx 50\text{W}$



**POD** Length: 450mm - OD :145mm - Aluminium – Weight 6,5Kg / 1,3Kg (Air/Water)



**Electrode** Length: 120mm - OD :90mm Aluminium - Weight 0,85Kg / 0,35Kg (Air/Water)

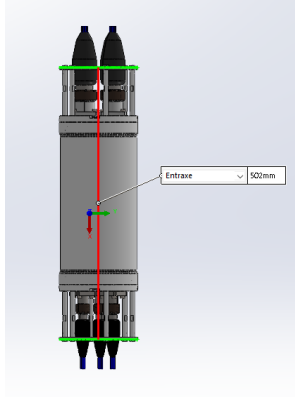




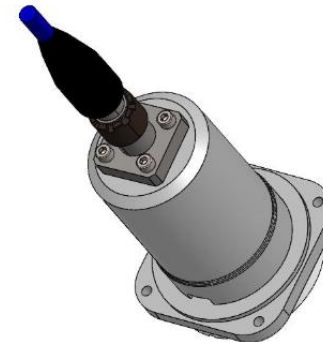
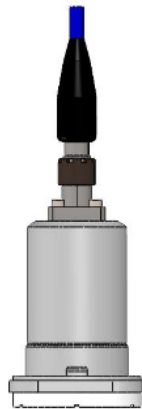
# Octopulse 6000m – up to 2\*8 electrodes – $\approx 60\text{W}$



**POD** Length: 520mm - OD :145mm - Titanium – Weight 12Kg / 7Kg (Air/Water)



**Electrode** Length: 120mm - OD :90mm - Titanium - Weight 1,5Kg / 0,95Kg (Air/Water)





# Software Modules



# UXO 2D SOFTWARE MODULE

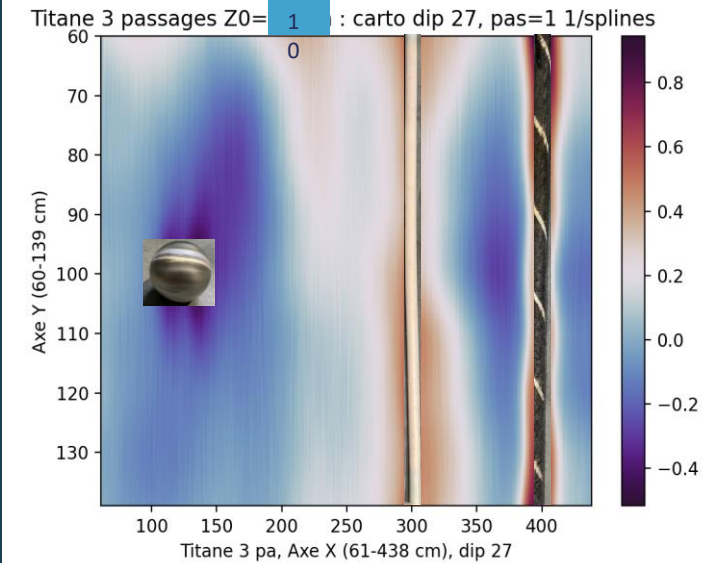
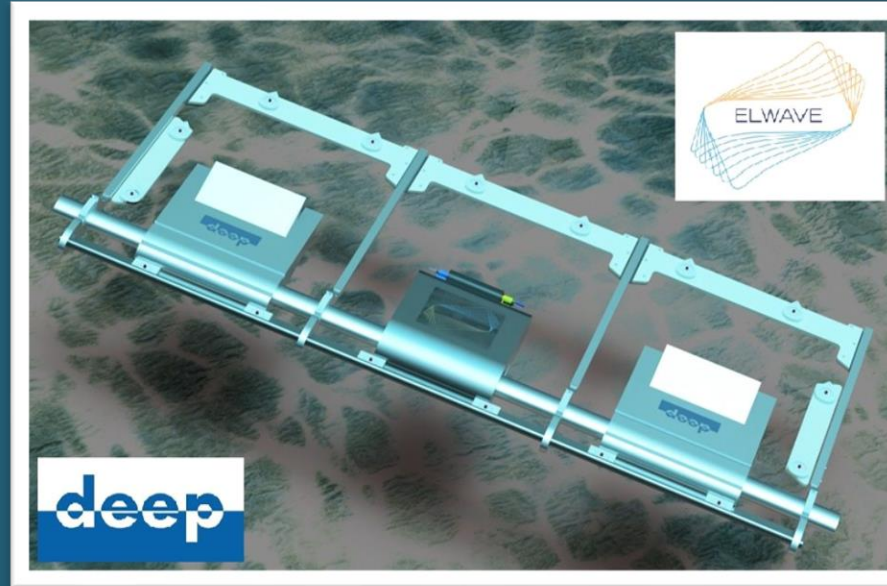
BURIED  
UXO

BURIED  
MINES

MARINE  
ARCHAEOLOGY

SEABED MINERAL  
RESSOURCES

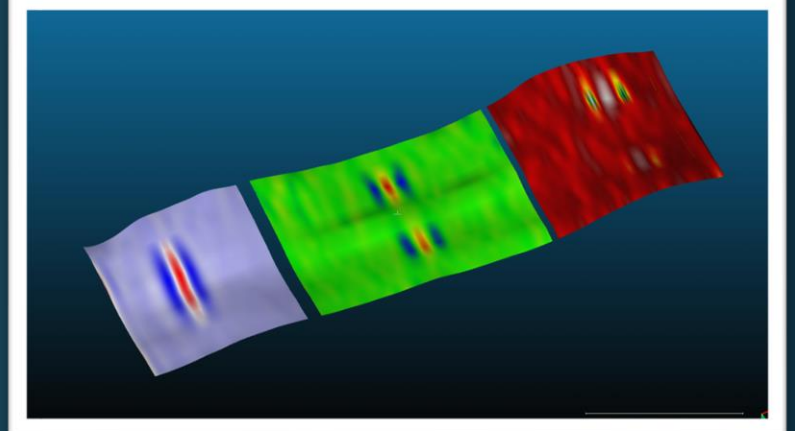
WRECK & DEBRIS



Buried conductive sphere and non-conductive communication cables

## DATA OUTPUT

- ✓ **POINTS CLOUD (X,Y,Z, seabed resistivity)** to export to 3rd party mapping software
- ✓ **UXO 3D SOFTWARE MODULE** will also provide a text file with individual buried object additional information (time, coordinates, DOB, shape, size, material conductivity).



# BURIED OBJECTS :Typical Detection capabilities



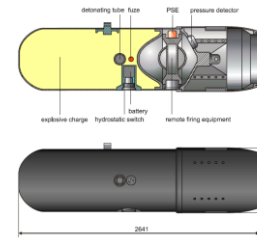
**20mm Fiber Optic cable**  
(non-conductive)



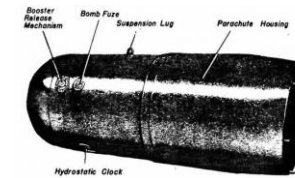
**24" Buried pipeline**  
(non-conductive)



**Buried LMB**  
(conductive & non ferro magnetic)



**Buried LMA**  
(conductive & ferro magnetic)



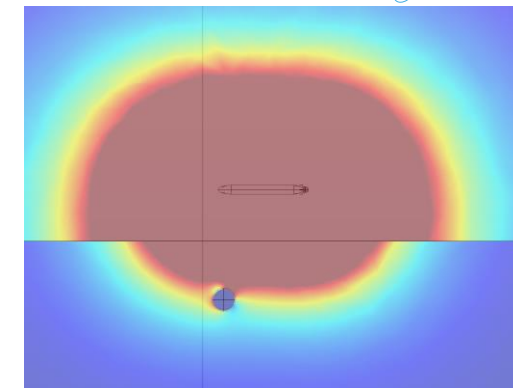
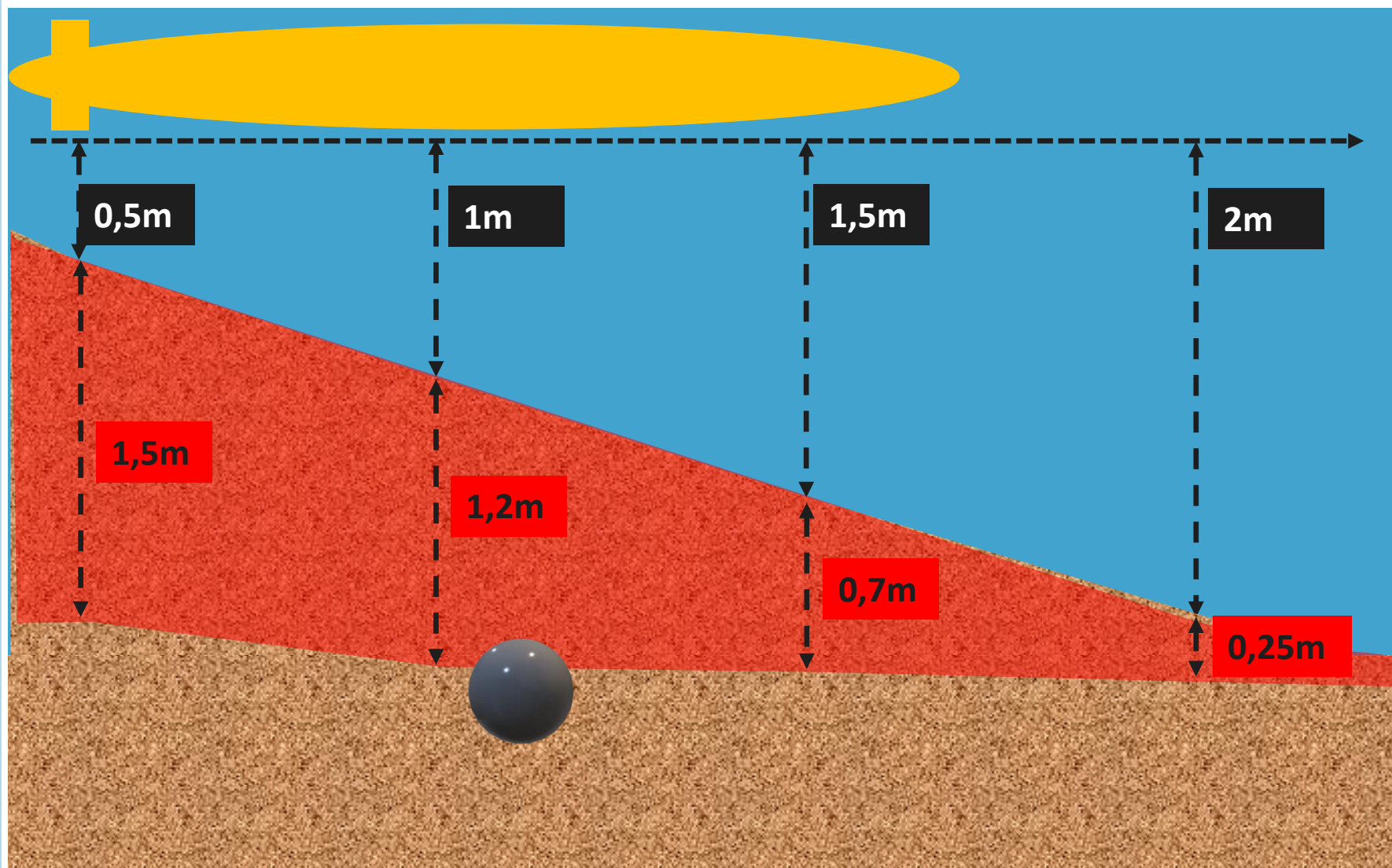
**Buried Manta**  
(non-conductive & non ferro magnetic)



Dipole length (vehicle dimension)	4m	1,5m	1,5m	4m	4m
Vehicle altitude	1m	3m	3m	7m	3m
Target Depth of Burial	0,5m	2m	2m	0,5m	0,5m



# Typical detection from a 4m long AUV

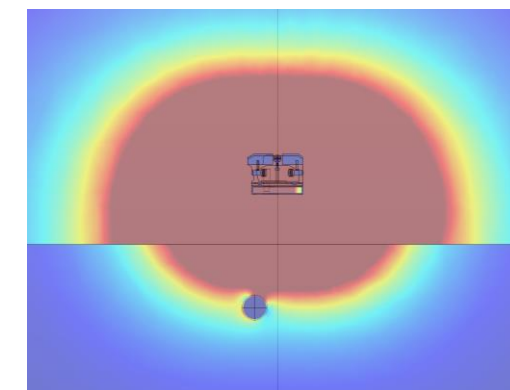
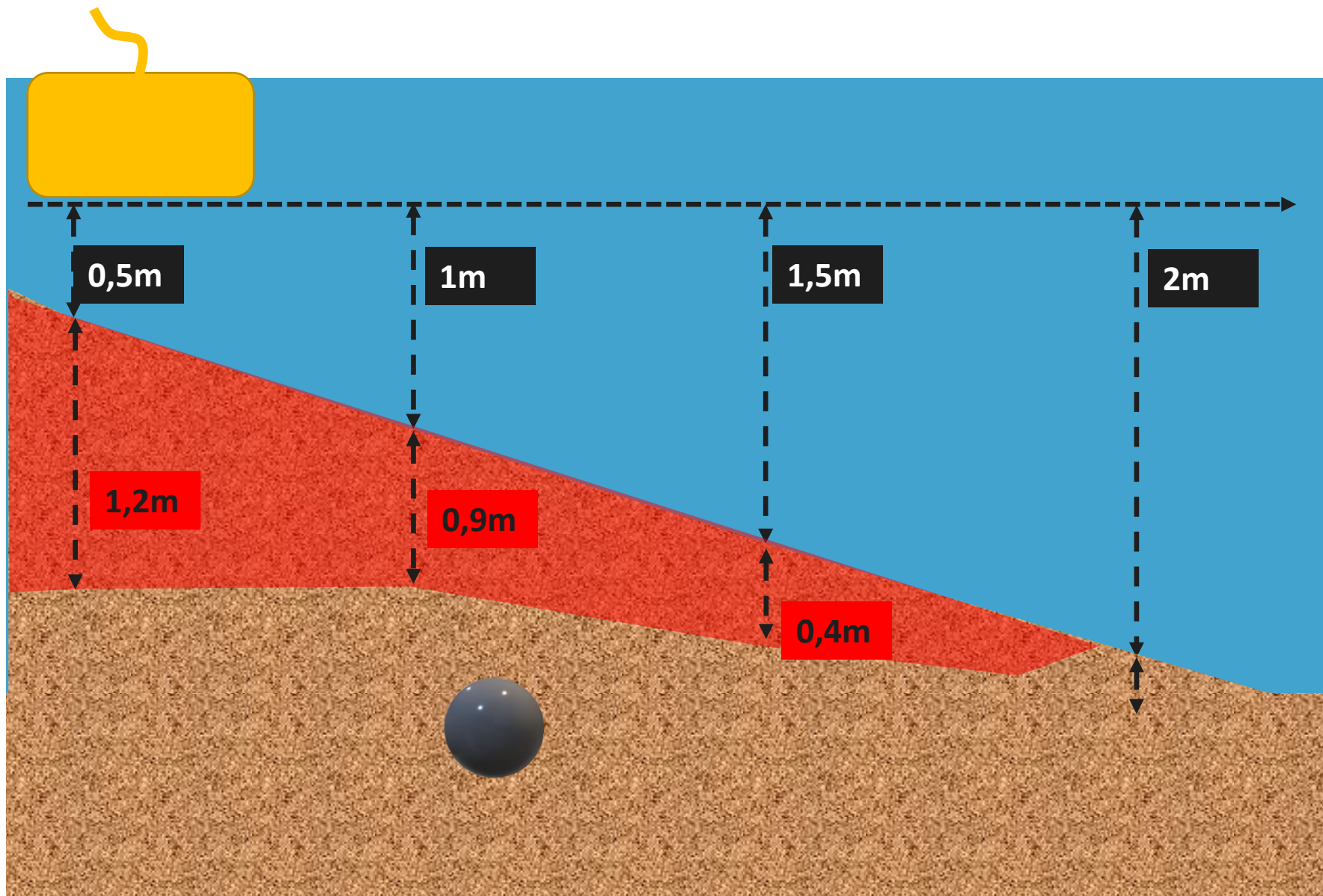



■ Detection coverage of a Ø0,5m sphere or volume equivalent **insulated** buried object

2m AUV altitude above seabed


0,7m Sphere max depth of burial

# Typical detection from a 1m long ROV



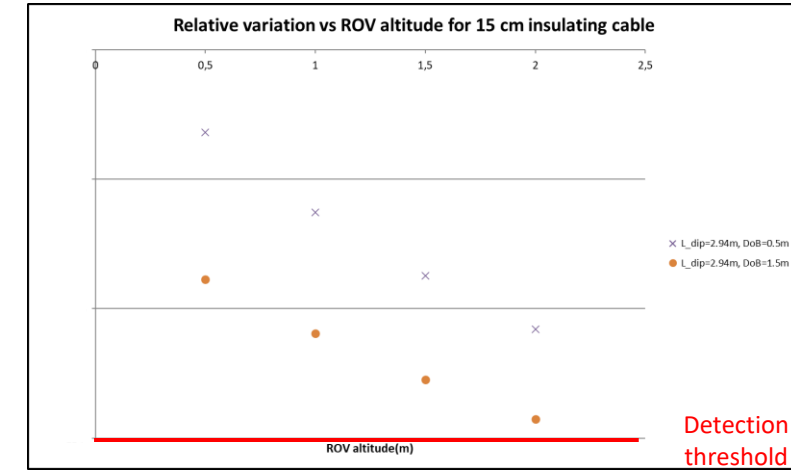
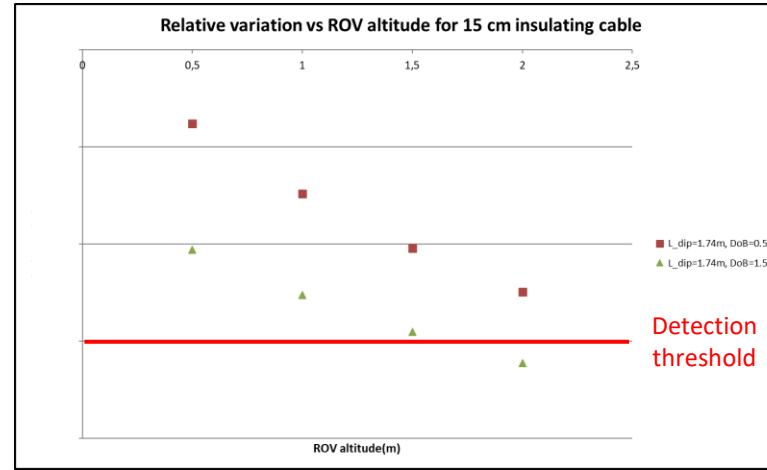
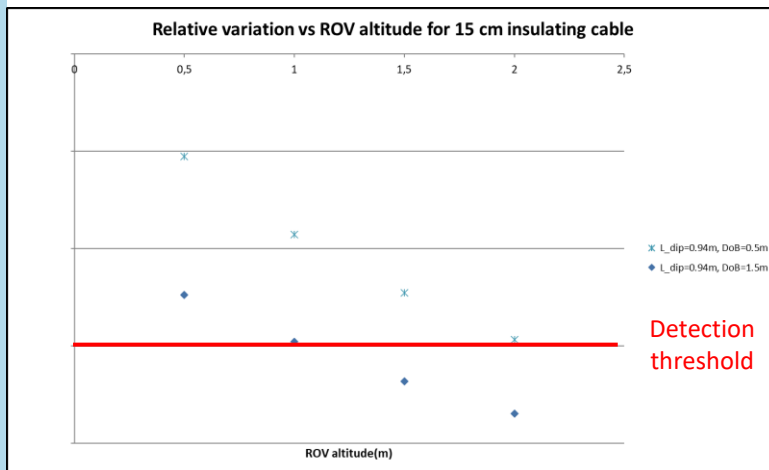
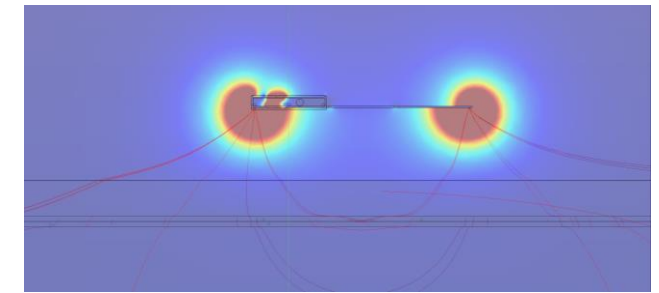
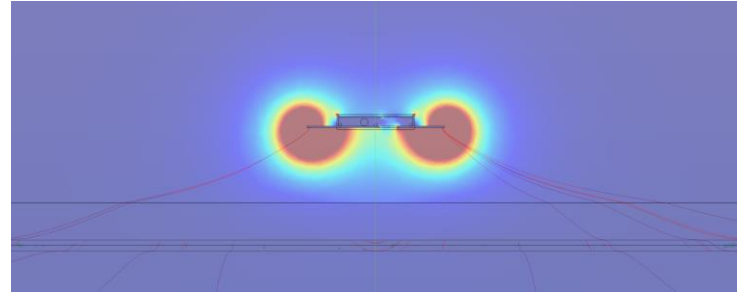
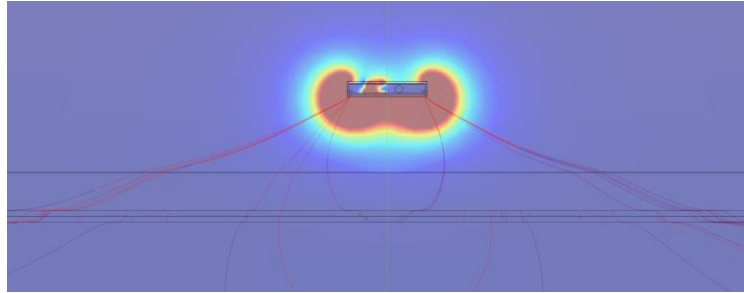
 Detection coverage of a  $\varnothing 0,5\text{m}$  sphere or volume equivalent **insulated** buried object

 2m ROV altitude above seabed

 0,4m Sphere max depth of burial



# Detection capabilities – 15cm cable



## 1m Skid


- ✓ 0,5m DoB cable : up to 2m altitude
- ✓ 1,5m DoB cable : up to 1m altitude

## 1,75m Skid

- ✓ 0,5m DoB cable : up to 2,3m altitude
- ✓ 1,5m DoB cable : up to 1,6m altitude

## 3m Skid

- ✓ 0,5m DoB cable : up to 2,7m altitude
- ✓ 1,5m DoB cable : up to 2,2m altitude

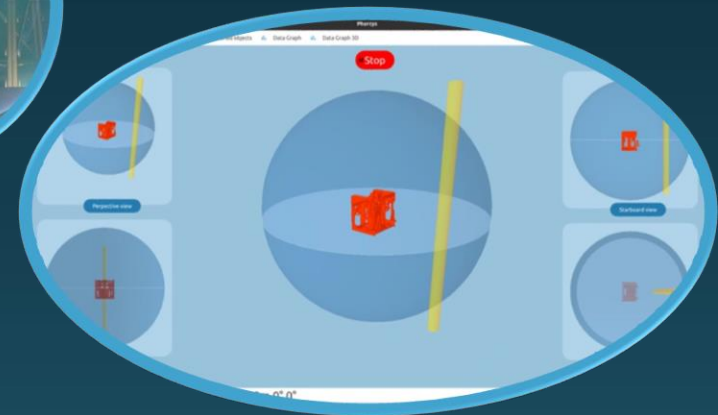
The background of the slide is a photograph of an offshore wind farm. Several white wind turbines are visible in the distance, standing on the ocean floor. The water is a deep blue with white-capped waves. The sky is a pale blue with soft, white clouds. A large, dark blue diagonal shape covers the right side of the image, and a white rectangular box with an orange border is positioned over the lower right portion of this shape.

Further  
capabilities...



# SAFETY SHIELD SOFTWARE MODULE

With its unique ability to detect and characterize (size, shape, electrical nature) any insulating and conductive objects in water, ELWAVE technology is a breakthrough solution for real time underwater perception with a **detection range up to 5 times the length of the vehicle**



REAL-TIME

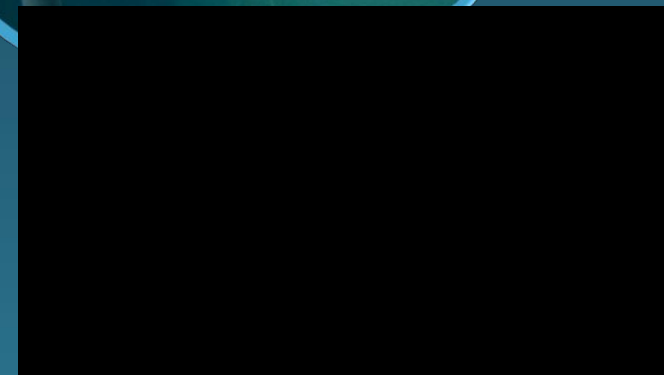
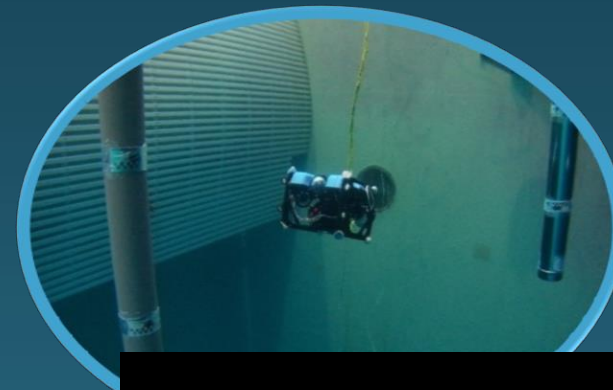
OMNIDIRECTIONAL

CONDUCTIVE & INSULATING OBJECT

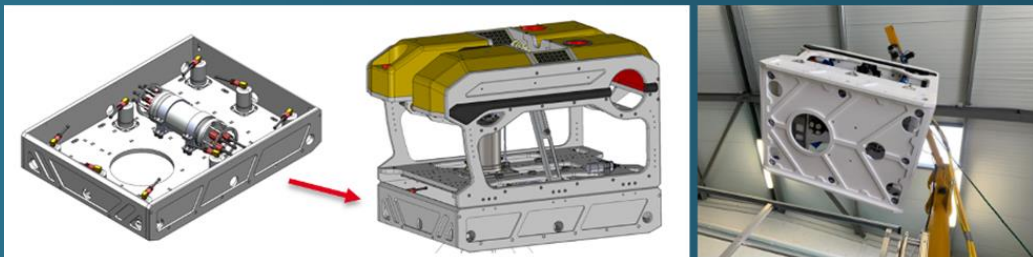
TURBID WATER

CLOSE APPROACH

OBSTACLE AVOIDANCE



# BURIED PIPELINE/CABLE TRACKING SOFTWARE MODULE



BURIED COMMUNICATION  
CABLES

BURIED ACTIVE & POWER  
CABLES

BURIED  
PIPELINES

BURIED MOORING LINES &  
ANCHORAGE

## DATA OUTPUT

- ✓ **Industry standard protocol** to export real-time Depth of Burial survey information to 3rd party survey software
- ✓ Real time lateral offset information can feed the subsea vehicle **auto-tracking mode**



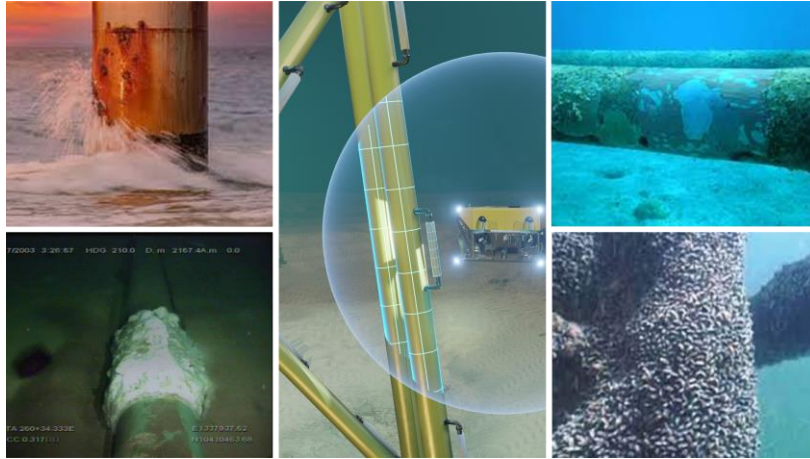


# Further Software Modules to come...



## Contactless

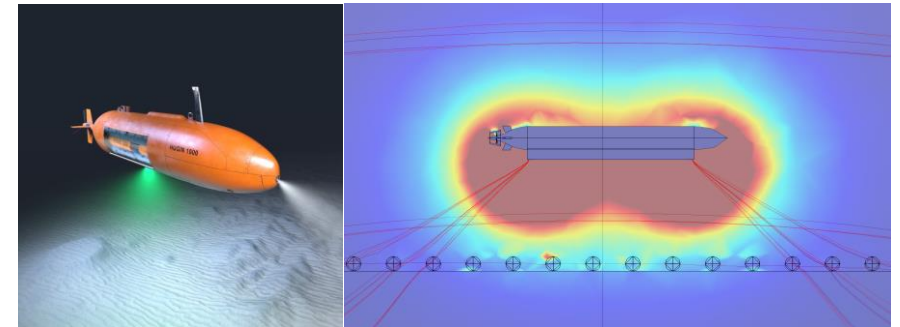
### Subsea Structure Inspection



- ✓ Biofouling weight estimation
- ✓ Pipeline coating crack detection
- ✓ Corrosion and Microbiology Influence corrosion detection
- ✓ Contactless cathodic protection monitoring

## Contactless

### Seabed Minerals Identification



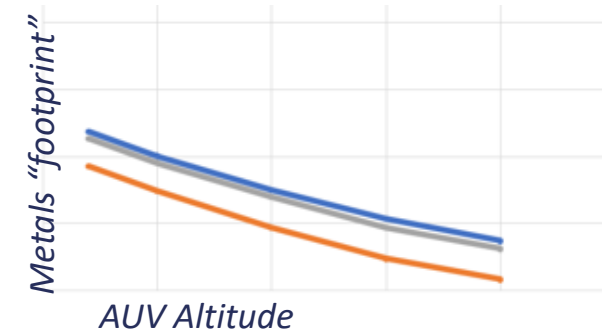
Massive sulphides minerals



Manganese



Quartz





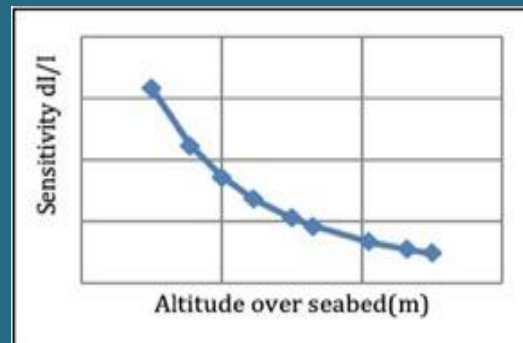
# EARLY ADOPTER's PARTNERSHIP



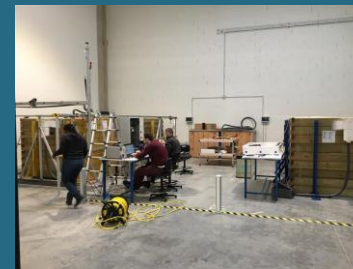
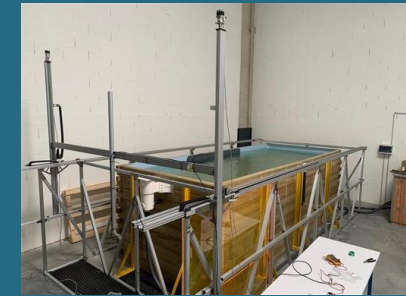
# EVALUATION PROCESS (*representativity* ≥95%)



## Numerical simulation



## Offshore Sea trials & preliminary preparation in pools on scale model



subsea 7



NAVAL  
GROUP

FUGRO

Evaluation process (numerical simulation + scaled model in pools) as an **highly efficient, cost effective, risk mitigation** way before integration and T&E on real vehicle.



2022

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